

## Lecture 8:Advanced Sockets

References for Lecture 8:

- 1) Unix Network Programming, W.R. Stevens, 1990,Prentice-Hall, Chapter 6.
- 2) Unix Network Programming, W.R. Stevens, 1998,Prentice-Hall, Volume 1, Chapter 3-4.

It is also possible to obtain the well-known address of a service or the name of a service on a specialized port.

```
#include <netdb.h>
struct servent *getservbyname(const char *servname, const char *portname);
-- Returns NULL on error. servname = "ftp" for example.
struct servent *getservbyport(int port, const char *portname);
-- returns NULL on error.
stuct servent{
    char    *s_name;    /* official server name*/
    char **s_aliases; /* list of aliases */
    int     s_port;    /*port number – network byte order */
    char    s_proto;   /* protocol to use */
};
```

## Socket Options

Like fcntl( ) for controlling file options, and msgctl/semctl/shmctl( ) for controlling message queue/semaphore/shared memory options, the following two functions are for controlling socket options.

```
#include <sys/socket.h>
int getsockopt(int sockfd, int level, int optname, void *optval, socklen_t *optlen);
int setsockopt(int sockfd, int level, int optname, const void *optval, socklen_t  optlen);
-- returns 0 if OK, -1 on error.
```

*sockfd* – an open socket descriptor;

*level* – who gets/sets the option: socket code, TCP/IP or XNS.

*optname* – predefined option name.

*optval* – pointer to the value to set or get. Most option values are integer type.

*optlen* – length of the option (size of the value), value-result for getsockopt( ); only useful for IP\_OPTIONS.

An option can be either a **flag** (on/off) or a **value** that can be set or retrieved. Some options can find their places in TCP header or IP header such as TCP\_MAXSEG and IP\_TOS; some cannot such as TCP\_NODELAY and SO\_MTU. Flag options use 0 for off and a nonzero value for on. If *optval* has a value of zero after a call to getsockopt( ), that option is currently off. See Figure 6.14 [Stevens ed1:p314].

**For TCP/IP, possible levels are:**

SOL_SOCKET	– for socket option,
IPPROTO_IP	– for Ipv 4 option,
IPPROTO_Ipv6	– for Ipv6 option,
IPPROTO_ICMPv6	– for ICMP version6 option,
IPPROTO_TCP	– for TCP option,

### Socket level options include:

SO\_BROADCAST –f– enable/disable broadcasting. Datagrams only.

SO\_DEBUG –f– used for TCP connection to return detailed information on packets

SO\_ERROR –f– returns the “so\_errno” ( defined in <sys/socketvar.h>) value for a socket error. Same value is also stored in Unix errno variable.

SO\_KEEPALIVE –f– when no data has been transmitted over a socket for 2 hours, a keepalive probe is sent. If no response is received after several probes are sent, the connection is closed. Used to detect abnormal termination.

SO\_LINGER –v– determines whether any unsent data should be sent or discarded when a socket is closed. Close may block until data is sent. Most value options are integer type, but this one uses

```
struct <sys/socket.h>
struct linger { int l_onoff; /* zero=off, nonzero=on */
                Int l_linger; /* linger time in seconds */ }
```

SO\_OOBINLINE –f– specifies that OOB data also be placed in the normal input queue.

### Ipv4 level options include:

IP\_OPTIONS –v– set or fetch options in the IP header.

IP\_TOS –v– specifies the type-of-service field in the IP header.

IP\_TTL –v– set or fetch the TTL(time-to-live) field – maximum number of hops.

### TCP level options includes:

TCP\_MAXSEG –v– returns the maximum segment size. The value is set when the connection is established.

TCP\_KEEPALIVE –v– changes the keepalive interval for this connection.

TCP\_NODELAY –f– prevents TCP from buffering data to create larger packets. Used for interactive application such as telnet.

```
#include <fcntl.h>
int fcntl(int fd, int cmd, int arg); /* See[Stevens ed 1: 41-43], here we only discuss socket-related cmds*/
-- returns 0 if OK, -1 on error.
fd – an open socket descriptor;
cmd – operation to be performed on fd.
val – the value to set or get.
```

Cmd:

- **fcntl(fd, F\_GETOWN / F\_SETOWN, arg):** get or set the associated process number (*arg* > 0) or the associated process group number (*arg* < 0) in order to receive SIGIO or SIGURG. Only available for terminals and sockets.
- **fcntl(fd, F\_GETFL / F\_SETFL, FNDELAY / FASYNC):** set or get file flag bits FNDELAY or FASYNC. FNDELAY affects accept, connect, read, write, recv, send, sendto and recvfrom. FASYNC enables the receipt of SIGIO.

Question: How many ways to set a nonblocking socket?

## Asynchronous I/O

Process can wait for the kernel to send signal SIGIO when a specified descriptor is ready for I/O. 3 things to do:

- 1) Establish a handler for SIGIO by calling signal(SIGIO, ???);
- 2) Set PID or PGID for the descriptor to receive SIGIO by calling fcntl(fd, F\_SETOWN, getpid());
- 3) Enable asynchronous I/O by calling fcntl(fd, F\_SETFL,FASYNC).

```
/* Copy standard input to standard output. */
#define BUFFSIZE 4096
main()
{   int      n;
    char     buff[BUFFSIZE];

    while ( (n = read(0, buff, BUFFSIZE)) > 0) write(1, buff, n);
}

/* Copy standard input to standard output, using asynchronous I/O. */
#include<signal.h>
#include<fcntl.h>
#define BUFFSIZE 4096
int sigflag;
main()
{   int      n;
    char     buff[BUFFSIZE];
    int      sigio_func();
    signal(SIGIO, sigio_func);           /* Step 1: set up signal handler*/
    fcntl(0, F_SETOWN, getpid());       /* Step 2: set descriptor's process ID*/
    fcntl(0, F_SETFL, FASYNC);         /* Step 3: Enable Asynchronous I/O*/
    for ( ; ; ) {
        sigblock(sigmask(SIGIO));       /* block signal SIGIO to avoid race condition */
        while (sigflag == 0)  sigpause(0); /* release signals when waiting for a signal.
                                            Note the difference between pause() and sigpause(0) */
        /* We're here if (sigflag != 0). Also, we know that the SIGIO signal is currently blocked.*/
        if ( (n = read(0, buff, BUFFSIZE)) > 0) write(1, buff, n); /* not a loop structure */
        else if (n == 0)    exit(0);      /* EOF */
        sigflag = 0;                 /* turn off our flag */
        sigsetmask(0);              /* and reenable signals */
    }
}

int sigio_func()
{   sigflag = 1;          /* just set flag and return */
    /* the 4.3BSD signal facilities leave this handler enabled for any further SIGIO signals. */
}
```

## Select( )

When a server (or client) has multiple connections, it can be difficult to guess which clients( or servers) have written data on a socket. One approach, called **polling**, is to use nonblocking recv( ) and loop through all the connections. This is inefficient. Another approach, using **fork( )**, is to fork a child process for each connections. This is also inefficient. A better option is to wait on all the connections simultaneously. This can be done using select( ) function.

```
#include <sys/select.h>
#include <sys/time.h>
int select (int maxfdp1, fd_set *readset, fd_set *writeset, fd_set *exceptset, const struct timeval *timeout);
-- returns # of ready descriptors, 0 if timeout occurs, -1 on error.
```

*maxfdp1* – the maximum descriptor to test +1, the possible number of descriptors to test,  $\leq 256$ .

*readset* – used to check which connections have data read.

*writeset* – used to check which connections have space for more output.

*exceptset* – used to check which connections have exceptions, such as OOB data.

*timeout* – specifies how long to block waiting for ready connection

There are three options;

= 0 means the call is nonblocking. Used for polling connections.

> 0 means the call times out after this amount of time if there are no ready connection during this time.

NULL means the call blocks until a connection is ready for I/O.

The format of the timeval structure is:

```
struct timeval {
    long tv_sec;    /*seconds*/
    long tv_usec;   /*microseconds*/
};
```

select( ) is used to determine which socket are ready for reading, writing, or exception handling. Use NULL for any fd\_set that doesn't need to be checked.

The fd\_set datatype typically uses one bit per socket fd. The appropriate method for using fd\_set is to zero out all the bits and then set each one that is to be tested. The select( ) call modifies the *readset*, *writeset*, and *exceptset* variables by clearing the bits that are not ready for I/O. The user then tests each bit to see which are set and processes the corresponding sockets.

Operations on fd\_sets should be performed using the following macros:

```
void FD_ZERO(fd_set *fdset);      /* clear all bits in fdset*/
void FD_SET(int fd, fd_set *dset); /* turn on the bit for fd in fdset */
void FD_CLR(int fd, fd_set *fdset); /* clear off the bits in fdset*/
int  FD_ISSET(int fd, fd_set *fdset); /* test the bit for fd in fdset */
```

See <sys/types.h> for definitions of sd\_set and FD\_XXX macros.

Example1:

```
int i, n;
fd_set fdvar;

FD_ZERO(&fdvar); /* initilize the Set --- all bits off */
FD_SET(1, &fdvar); /* turn on bit for fd 1 */
FD_SET(4, &fdvar); /* turn on bit for fd 4 */
FD_SET(5, &fdvar); /* turn on bit for fd 5 */

If ((n=select(6, &fdvar, NULL, NULL, NULL))<0) printf("Something wrong!\n");
/* only want to check the readset.*/

for (i=0, i<6, i++) if (FD_ISSET(i, &fdvar)>0) handle(i); /* fd i had data for read, call handle(i) */
```

Example2:

```
#include "unp.h"
void str_cli(FILE *fp, int sockfd)
{   int         maxfdp1;
    fd_set      rset;
    char       sendline[MAXLINE], recvline[MAXLINE];

    FD_ZERO(&rset);
    for ( ; ; ) {
        FD_SET(fileno(fp), &rset);
        FD_SET(sockfd, &rset);
        maxfdp1 = max(fileno(fp), sockfd) + 1;
        Select(maxfdp1, &rset, NULL, NULL, NULL);

        if (FD_ISSET(sockfd, &rset)) { /* socket is readable */
            if (Readline(sockfd, recvline, MAXLINE) == 0)
                err_quit("str_cli: server terminated prematurely");
            fputs(recvline, stdout); }

        if (FD_ISSET(fileno(fp), &rset)) { /* input is readable */
            if (Fgets(sendline, MAXLINE, fp) == NULL)
                return; /* all done */
            writen(sockfd, sendline, strlen(sendline)); }
    }
}
```

Notes: select( ) can be used for a more accurate timer than sleep( ).  
select() can be used for waiting for a connection request.

## Socket-related Signals:

### 1) SIGIO :

- indicates that a socket is ready for asynchronous I/O as we have discussed.
- need to specify process ID or process group ID to receive the signal.
- Need to enable asynchronous I/O.

### 2) SIGURG:

- indicates urgent data is coming due to 1)OOB data or 2) control status information.
- need to specify process group ID to receive the signal,e.g., fcntl(sd,F\_SETOWN, -getpgid( )).
- Use flag=MSG\_URG to send and receive the OOB data.
- If O\_OOBINLINE is set, we must use STOCATMARK ioctl to read OOB data.

```
setsockopt(sd, SOL_SOCKET, SO_OOBINLINE, &seton, sizeof(seton)); /*let seton=1*/  
if ((n=ioctl(sd,STOCATMARK, &start)>0) read(sd, buf, n); /*OOB data is in buf with n bytes.*/
```

### 3) SIGPIPE:

- indicates socket, pipe, or FIFO can never be written to.
- Sent only to the associated process,

## Internet Superserver --- inetd

### How many typical network servers?

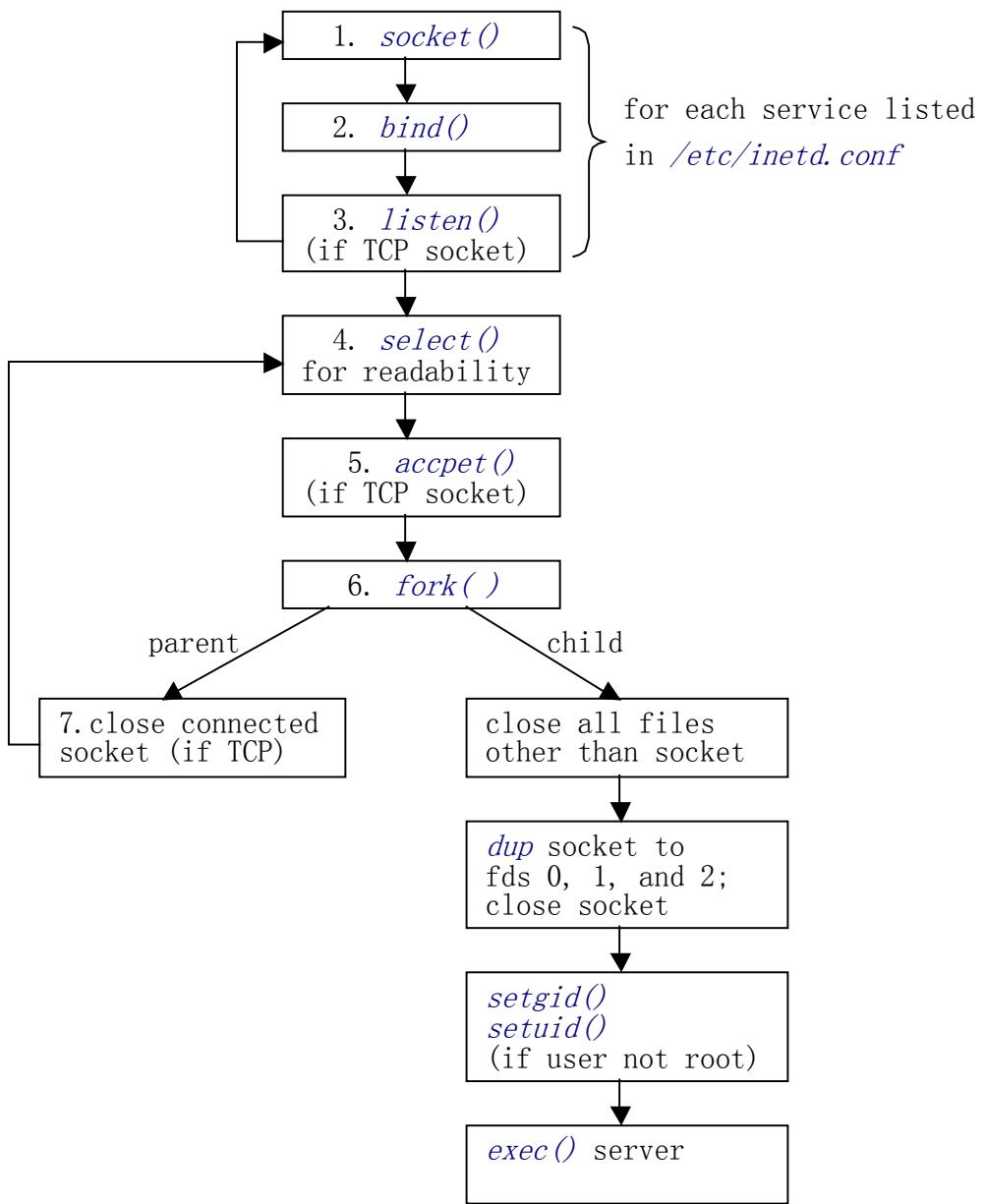
- telnet, ftp, tftp, remote login, remote shell
- started from /etc/rc
- did the same startup tasks: socket, bind, listen, accept, fork, ...

### How to use select( ) to combine them into one daemon?

- 4.3 BSD supersever: inetd
- reduce the number of processes
- simplify the writing of daemon processes since they have the same startup tasks and skeleton daemon tasks (see Lecture 1 for skeleton daemon).

### Flow chart of inetd (version2: section 12.5 or version1:section 6.16)

- 1) read /etc/inetd.conf to create one socket for each service in the file.
- 2) read /etc/services to bind well-known port numbers to each service.
- 3) Listen() only for TCP.
- 4) Select() can be used for connect requests that arrives at the socket for reading.
- 5) If it is TCP request, call accept().
- 6) Fork a child process to handle the request
  - 6.1) close all files except socket
  - 6.2) dup2(sd,0), dup2(sd,1), and dup2(sd, 2).
  - 6.3) login program: a superuser can become any user. Must in the order of setgid() first and then setuid().
  - 6.4) exec() to execute server\_program accordingly.
- 7) Parent goes up to accept next request without wait.



Steps performed by `inetd`